

# Cell Stiffening in Response to External Stress is Correlated to Actin Recruitment

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**ABSTRACT** We designed a micromanipulation device that allows the local application of a constant force on living cells, and the measurement of their stiffness. The force is applied through an Arg-Gly-Asp-coated bead adhering on the cell and trapped in optical tweezers controlled by a feedback loop. Epifluorescence observations of green fluorescent protein-actin in the cells are made during force application. We observe a stiffening of cells submitted to a constant force within a few minutes, coupled to actin recruitment both at the bead-cell contact and up to several micrometers from the stress application zone. Moreover, kinetics of stiffening and actin recruitment exhibit a strong correlation. This work presents the first quantification of the dynamics of cell mechanical reinforcement under stress, which is a novel insight into the elucidation of the more general phenomenon of cell adaptation to stress.

## INTRODUCTION

Adherent cells are highly sensitive to their mechanical environment which they feel through adhesion molecules embedded in the cell membrane. Among these various binding proteins, integrins link the extracellular matrix to the cell actin cytoskeleton via a dynamic complex of proteins (1,2). These clusters, named focal adhesions (FA), are several micrometers in size and act as mechanosensors (3).

Cellular response to the mechanical environment is based on the mechanotransduction that occurs within FA, and implies processes that happen on very different timescales. Long-term responses include, for example, adaptation of the traction force to the substrate rigidity (4), spreading (5), motility (6–8), or even control of the cell cycle (differentiation, apoptosis) (9–11). Shorter-term responses involve both physiological and mechanical phenomena: mechanical strengthening (12), growth and modification of the biological composition of the existing contacts (13,14), assembly of new focal complexes (15), and enhanced contractility of the actin cytoskeleton (16). Yet the broad cascade of biochemical signaling (17–19) involved in mechanotransduction at the cell membrane has not been totally elucidated.

Cells mechanical integrity is crucial for these adhesion-dependent mechanisms. Hence viscoelastic behaviors of the cells have been widely studied in the aim of establishing a link between their mechanical properties and the biological state of their cytoskeleton (20–23). These investigations lead to identifying actin filaments, and the acto-myosin contractility in particular, as major components of the cells viscoelastic response (24,25) and of their adaptation to stress (4,26).

We set out to focus on the process of cell stiffening under stress that has already been reported previously. It has been shown, for instance, that focal contacts are strengthened by the application of an external force (12) and grow in the direction of the applied force (18). The application of a fluid shear stress on adherent cells causes a dramatic increase in their viscosity, and the actomyosin contractility has been shown to be involved in this process (27). By applying a local force it has also been shown that cell rigidity increases (28) and actin remodels in the vicinity of the applied force (29,30).

To investigate the link between these phenomena and to quantify their dynamics, we designed a method that allows us to both locally apply a constant force, and make epifluorescence observations. Force application is performed via an optically trapped silica microbead. The bead position is measured on a quadrant photodiode detector (see Supplementary Material Fig. S1). A feedback loop (31) is implemented to keep the force on the bead constant. We measure the local creep function and retrieve the cell viscoelastic parameters. We apply a temporal series of step forces so as to have access to the evolution of cell stiffness, and we compare it to the reorganization of green fluorescent protein(GFP)-actin in the cell. We show that the rigidity and the quantity of actin in the vicinity of the force application zone both increase, and that the kinetics of these two phenomena are very well correlated. We propose a typical timescale for actin recruitment and cell stiffening.

## MATERIALS AND METHODS

### Cell preparation

Both A549 human alveolar epithelial cells (American Type Culture Collection, Rockville, MD) and C2C12 mice myoblastic cells, kindly provided by M. Lambert (Institut du Fer à Moulin, Paris, France), were cultured in Dulbecco's modified Eagle's medium supplemented with 10% fetal calf serum, 2 mM glutamine, 100 U/mL penicillin, and 50 mg/mL streptomycin

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(Invitrogen, Carlsbad, CA). Twenty-four hours before manipulation, cells were detached from culture flasks with a trypsin-EDTA solution and plated on a glass coverslip coated with 5  $\mu\text{g/mL}$  fibronectin (Sigma, St. Louis, MO). For epifluorescence observations, GFP-actin plasmid transfection was performed with nanofectin (PAA Laboratories, Pasching, Austria), according to the manufacturer's procedure,  $\sim 15$  h before experiment. The plasmid was kindly provided by M. Coppey (Institut Jacques Monod, Paris, France).

## Bead coating

Carboxylated silica beads (3.47  $\mu\text{m}$  diameter; Bangs Laboratories, Fishers, IN) were coated with a polypeptide containing the Arg-Gly-Asp (RGD) sequence (PepTide 2000; Telios Pharmaceuticals, San Diego, CA), according to the manufacturer's procedure. It ensured a specific binding to integrin receptors. Beads were then incubated on cells at 37°C for 15 min before manipulation (1–3 beads per cell).

## Force application

Our optical tweezers setup, represented in Supplementary Material Fig. S1, is based on a 1064 nm Nd:YAG laser, 600 mW intensity (Spectra Physics, Mountain View, CA), which is focused through the objective of an inverted microscope (model No. DM IRB,  $\times 100$  oil immersion objective, 1.25 NA; Leica, Wetzlar, Germany). Galvanometric mirrors are used to deflect the laser beam, and thus displace the optical trap in the  $XY$  plane. The position of the bead in the  $XY$  plane,  $\mathbf{r}_{\text{bead}}$ , is measured on a quadrant photodiode (S1557; Hamamatsu, Hamamatsu City, Japan). Its spatial resolution is limited by several noise sources: light intensity fluctuations, amplification, and sampling devices noises. The raw acquired signal yields the bead position with a 50 nm resolution. The use of a quadrant detector is essential to achieve a high temporal resolution (much higher than could be achieved through the use of a charge-coupled device camera with an image analysis software), and allows an averaging of the signal over four running data points. This eventually decreases the error on the position down to 25 nm.

The quadrant diode electrical signal is amplified as described by Simmons et al. (31), yielding the analogical value  $V_{\text{diode}} = (V_X, V_Y) = (A X_{\text{bead}}, A' Y_{\text{bead}})$ . The proportional coefficients  $A$  and  $A'$  are calibrated before each experiment. The experimental chamber is mounted on an  $XYZ$  piezoelectric nanopositioning device (NanoCube, Physik Intrumente, Karlsruhe, Germany), fixed to the microscope stage to allow precise movements of the experimental chamber in three dimensions.

Before any experiment, trap force calibration is performed using the hydrodynamic flow method described in more detail by Balland et al. (24). It gives  $F_{\text{trap}}$  as a nearly linear function of the distance  $\delta r$  from the center of the bead and the center of the trap:  $\|\delta \mathbf{r}\| = \|\mathbf{r}_{\text{bead}} - \mathbf{r}_0\|$  for  $0 \leq \delta r \leq 1.5 \mu\text{m}$ . Trap stiffness, depending on the laser power, lies within the range 35–120 pN/ $\mu\text{m}$ .

To apply a constant force on the bead, in modulus and direction,  $\delta \mathbf{r}(t)$  is kept constant by moving the piezoelectric stage on which the chamber is mounted. This is achieved numerically by a feedback loop under LabVIEW (National Instruments, Austin, TX). The program samples  $V_{\text{diode}}$  at 180 Hz and commands the piezo stage movement  $\mathbf{r}_{\text{piezo}}(t)$  with a 45 Hz bandwidth. The piezo stage response time is of  $\sim 0.02$  s, but the response time of the whole feedback loop depends on the cell rigidity. For very weak cells, large instantaneous displacements are required at  $t = 0$ . The force clamp reaches its full efficiency within a maximum time  $T_{\text{max}} = 0.1$  s. Hence, we measure the instantaneous displacement of the bead with respect to the cell  $\mathbf{r}(t) = -\mathbf{r}_{\text{piezo}}(t)$  in response to a constant force  $\mathbf{F}_0$ .

## Measurement of the creep function

When a constant stress is applied to a material ( $\sigma = 0$  when  $t < 0$ ,  $\sigma = \sigma_0$  when  $t \geq 0$ ), the creep function is defined as

$$J(t) = \varepsilon(t)/\sigma_0, \quad (1)$$

where  $\varepsilon(t)$  is the induced strain. Here we apply a constant force step  $F_0$  and measure the bead displacement  $r(t)$ . The relationships between force and stress, respectively, and displacement and strain, in a simple linear elasticity model described previously (32), yields

$$J(t) = \frac{2\pi R f(\theta) r(t)}{F_0}, \quad (2)$$

where  $R$  is the bead radius (1.735  $\mu\text{m}$ ) and  $\theta$  is half the angle of the immersion cone of the bead into the cell. The value  $\theta$  is roughly estimated for each cell on transmission images (refer to (23,32) and Supplementary Material Fig. S2 for more details). The geometrical factor  $f(\theta)$  is given by

$$\frac{1}{f(\theta)} = \frac{9}{4 \sin \theta} + \frac{3 \cos \theta}{2 \sin^3 \theta}. \quad (3)$$

## Fluorescence detection

To follow the evolution of actin density around the bead, we visualize GFP-tagged actin in the cell using the same objective as for trapping. Before experiment, and after each step force application and measurement of the creep function, at time  $t_k$  ( $k = 1 \dots N$ ) a stack of epifluorescence images along the  $z$  axis is captured with a charge-coupled device camera (Coolsnap ES; Roper Scientific, Trenton, NJ) using an ImageJ plugin. The images are then processed using another ImageJ procedure: for each time  $t_k$  we define a set of four planes along the  $z$  axis (located around the plane of force application, and separated by  $\sim 1 \mu\text{m}$ ) over which we average the fluorescence intensity. In this averaged image, we choose different regions of interest (ROI):  $ROI_{\text{bleach}}$ , and  $ROI_i$ ,  $i = 1$  to 9.

$ROI_{\text{bleach}}$  is a control region, taken in the cell far enough from the bead center ( $\sim 6\text{--}8 \mu\text{m}$ ) not to be modified by the local force application. The average intensity in this zone,  $I_{\text{bleach}}$ , is used as a reference to check the degree of bleaching during the course of the experiment.  $ROI_i$  are disks of radii  $R_1 = 2.25$  to  $R_9 = 6.25 \mu\text{m}$  ( $R_{i+1} - R_i = 0.5 \mu\text{m}$ ) centered on the bead.

$ROI_2$ , which is approximately twice the area of the bead itself, is named  $ROI_{\text{bead}}$ , and contains the information about short-range actin recruitment around the bead. In this region, bright patches of actin appear at the bead-cell contact during the experiments (see Fig. 3). To evaluate the quantity of actin they contain, we identify and label the patches by indices  $p$  using an image treatment that is similar to the one described by Zamir et al. (33). We calculate the area  $A_p$ , and average intensity  $\langle I_p \rangle$  of each patch  $p$  and the quantity of actin recruited at the bead-cell contact at time  $t_k$ , is eventually estimated as

$$Q = \frac{1}{I_{\text{bleach}}} \sum_p A_p \times \langle I_p \rangle. \quad (4)$$

These patches are fitted by ellipses, from which we retrieve the major and minor axes and the orientation angle (see Fig. 4). We also evaluate the actin present in the network around the bead, by the average fluorescence intensity in  $ROI_{\text{bead}}$ , still taking into account the bleaching factor:

$$Q' = \frac{I_{\text{bead}}}{I_{\text{bleach}}}. \quad (5)$$

We perform the same measurements,  $Q'_i$ , in the disks  $ROI_i$ . Then, we calculate the average intensity in successive rings around the bead, of radii  $\delta R_i = (R_{i+1} + R_i)/2$ , by retrieving the differential quantities  $\delta Q'_i$ :

$$\delta Q'_i = \frac{\pi R_{i+1}^2 Q'_{i+1} - \pi R_i^2 Q'_i}{\pi (R_{i+1}^2 - R_i^2)}. \quad (6)$$

The values of  $Q'_i$  and  $Q$  are related to actin quantities but are not directly proportional to them. This is why they are only used relatively to the values measured at different times  $t_k$  within a given experiment.

## RESULTS AND DISCUSSION

### Creep function and cell viscoelastic parameters

We performed measurements on several cells of two different cell lines: A549 human alveolar epithelial cells and C2C12 mice myoblastic cells. By applying a constant stress on a cell through a RGD-coated bead, and measuring the resulting strain, we retrieved the local creep function (see Materials and Methods). Fig. 1 *A* shows a typical example of creep

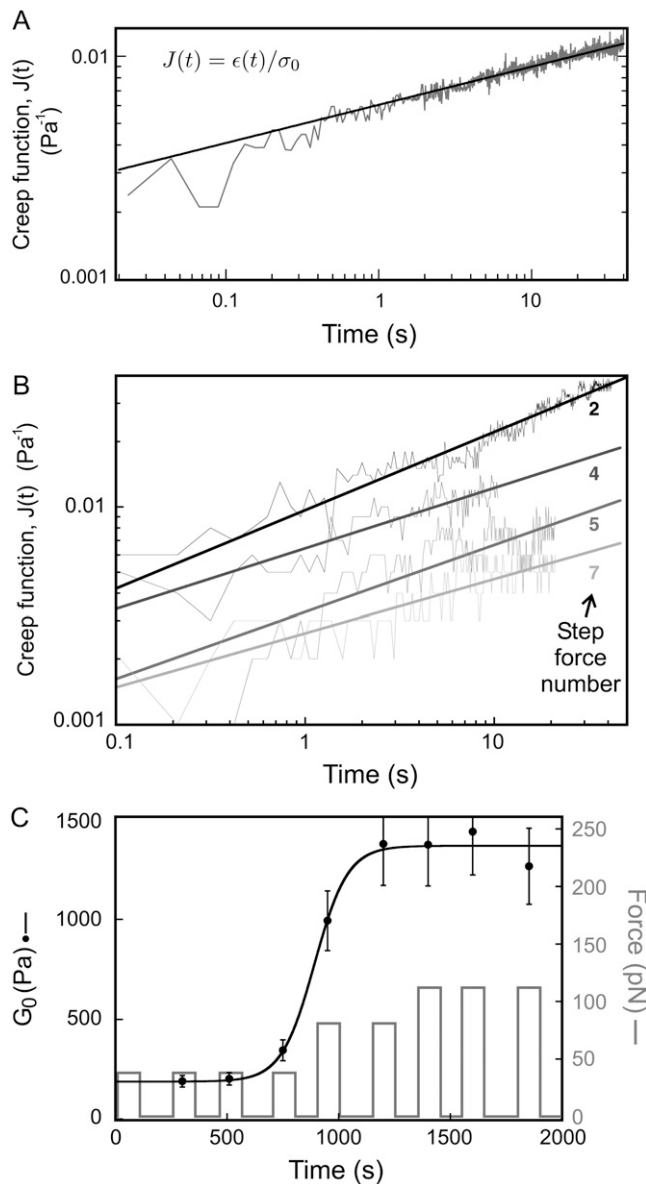


FIGURE 1 Mechanical measurements on single cells. (A) Creep function of a single C2C12 cell as a function of force application time, fitted by a power law  $J(t) = 5.9 \cdot 10^{-3} t^{0.18} \text{ Pa}^{-1}$  (in log-log scale). (B) Successive creep functions on a single A549 cell: a series of step forces is applied. For each step, the creep function is measured. For better readability,  $J(t)$  is displayed for only four of the nine-step force applications: number 2, 4, 5, and 7. (C) The corresponding viscoelastic modulus  $G_0$  versus time, fitted by a sigmoid with a rising time  $\tau_G = 75$  s. Mechanical saturation is reached in this example.

function measured on a C2C12 cell. It is well fitted by a power law over more than two time decades:  $J(t) = A (t/t_0)^\alpha$ , where  $t_0$  is a reference time, chosen here equal to 1 s. The fit yields  $\alpha = 0.18 \pm 0.01$  and  $A = 5.9 \pm 0.8 \times 10^{-3} \text{ Pa}^{-1}$  on this particular example (see Supplementary Material Note S4).

This weak power law, with an exponent of 0.1 to 0.5, is characteristic of the rheology of cells and more generally of materials having a large number of relaxation times distributed over a broad timescale (20,22,23,34).

To interpret our results in terms of cell rigidity, and to compare them with previous measurements, we retrieve the equivalent viscoelastic modulus at 1 Hz,  $G_0$ . For a creep function that is a power law,  $G_0$  is calculated from  $A$  and  $\alpha$  using the relation

$$G_0 = \frac{(2\pi)^\alpha}{A\Gamma(1+\alpha)}, \quad (7)$$

which has been demonstrated previously (23) ( $\Gamma$  is the Euler  $\gamma$ -function). For example, the creep measurement displayed on Fig. 1 *A* yields  $G_0 = 257 \pm 38 \text{ Pa}$  (see Supplementary Material Fig. S3 and Note S4 for comments on the error estimates).

Statistical repartitions show a Gaussian (or normal) distribution for the power-law exponent  $\alpha$ , and a log-normal distribution for the prefactor  $G_0$ , as evidenced on Fig. 2. The mean values and widths of the distributions are obtained by

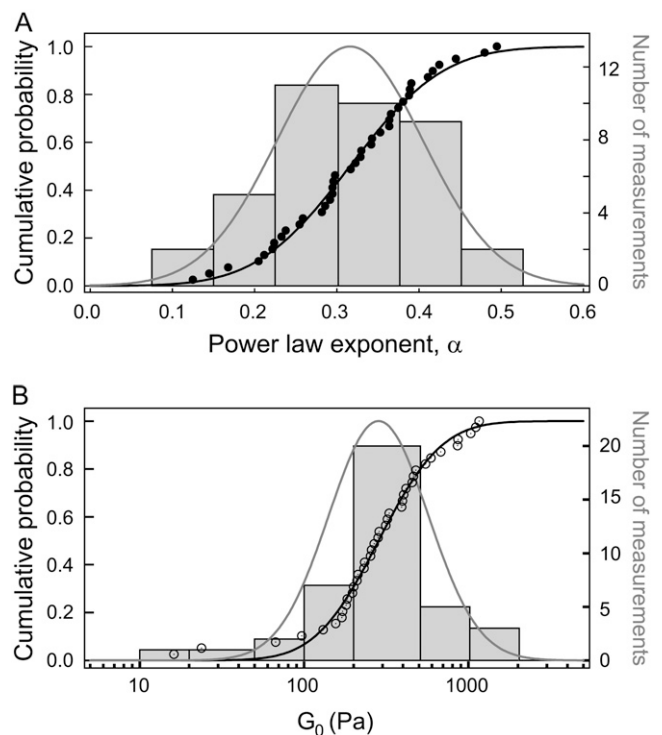


FIGURE 2 Distribution histograms and cumulative probability functions of the power-law parameters: exponent- $\alpha$  (A) and viscoelastic modulus  $G_0$  (B), measured on 39 different C2C12 cells.

fitting the cumulative probabilities of both  $\alpha$  and  $\log(G_0)$  by error functions:

$$E(x) = \frac{1}{2} + \frac{1}{2} \operatorname{erf} \left( \frac{x - \langle x \rangle}{\sigma \sqrt{2}} \right) = \frac{1}{2} + \frac{1}{\sigma \sqrt{2\pi}} \int_0^x \exp \left( -\frac{(u - \langle u \rangle)^2}{2\sigma^2} \right) du. \quad (8)$$

The average values and distribution widths measured for the power-law exponent  $\alpha$ , and the median value of the viscoelastic modulus  $G_0$  are  $\langle \alpha \rangle = 0.300$ ,  $\sigma_\alpha = 0.100$ , and  $G_{0, \text{med}} = 305$  Pa on A549 cells; and  $\langle \alpha \rangle = 0.316$ ,  $\sigma_\alpha = 0.089$ , and  $G_{0, \text{med}} = 285$  Pa on C2C12 cells. The mechanical parameters obtained for all the tested cells are summarized in Table 1. These results are consistent with previous measurements on cells probed locally or globally, for harmonic or quasistatic forcings (see data reported in (20–24,34)) and with passive microrheology measurements (35,36). Our data corroborate a large set of mechanical measurements performed on different cell types, which leads us to assert that our estimate of the viscoelastic modulus  $G_0$  is a reliable measurement of the local cell stiffness.

### Rigidity evolution on long timescales

To investigate the dynamics of mechanical response under external stress, we followed the evolution of cell rigidity during force application. The magnitude of the applied force was set between 40 and 180 pN. We applied a series of 150 s step forces and measured the creep function during each step. Each step force was followed by an equal time-lapse left for mechanical relaxation of the cell. The main reason for applying a series of force steps rather than a continuous force was to keep the cell deformation small, to remain within the linear regime for strain. The creep function measurements are performed over the maximum time range 0.02–50 s, during which major cell movements or mechanical shifts in the setup can be considered negligible. The reason for using nonmotile cells (C2C12 myoblastic cell line) and for avoiding beads attached to a lamellipodium-like region was to limit the disturbing effects due to membrane ruffling and actin retrograde flow.

A typical series of measurements performed on a single A549 cell is shown in Fig. 1 B. The creep function clearly decreases with the step force application number, meaning that the cell deforms less and less as a force is exerted on it. The cell still exhibits a power law rheology in the time range of 0.1 to 10–20 s, with an exponent  $\alpha$  that almost remains the same, but a prefactor  $A$  that gets smaller. Hence the modulus

$G_0$ , which gives the value of the local cell rigidity, increases. We can quantify the stiffening dynamics by plotting the variations of  $G_0$  versus time (see Fig. 1 C). For approximately two thirds of the cells tested, we observed such an increase in the cell rigidity in response to force application. All the stiffening curves exhibit a sigmoidlike behavior, even if the saturation in the value of  $G_0$  is not always reached. To restrain to a small number of fitting parameters and get results that can easily be displayed as a whole, we use a dimensionless viscoelastic modulus  $g(t)$ :

$$g(t) = \frac{G_0(t) - G_{0, \text{min}}}{G_{0, \text{max}} - G_{0, \text{min}}}. \quad (9)$$

$G_{0, \text{min}}$  and  $G_{0, \text{max}}$  are, respectively, the minimum and maximum values measured during the course of the experiment. The value  $g(t)$  can then be fitted by a sigmoid function,

$$g(t) = \frac{g_f}{1 + \left( \frac{g_f}{g_0} - 1 \right) \exp \left( -\frac{t}{\tau_G} \right)}, \quad (10)$$

with a set of three fitting parameters:  $g_f$ ,  $g_0$ , and  $\tau_G$ . The value  $\tau_G$  is the stiffening time;  $g_0$ , which is close to zero, takes into account the fact that the first measured value  $G_0(t_0)$  is not exactly equal to the modulus of the cell at rest, since we exert a perturbation as soon as we start measuring the cell viscoelasticity. The parameter  $g_f$  is approximately equal to 1 if mechanical saturation is reached (that is, if the last measured value  $G_0(t_N)$  is the cell maximum response to stress), otherwise  $g_f \geq 1$ . In Fig. 1 C, for example,  $G_{0, \text{min}} = 190$  Pa,  $G_{0, \text{max}} = 1355$  Pa,  $g_0 = 7.3 \cdot 10^{-7}$ ,  $g_f = 1.08$ , and  $\tau_G = 90$  s for this A549 cell.

Table 2 summarizes the values obtained for C2C12 cells. Between the first and the last step force application, the value of the viscoelastic modulus  $G_0$  increases by almost one order of magnitude:  $G_{0, \text{min}}$  is typically of  $\sim 250$  Pa while  $G_{0, \text{max}}$  is  $\sim 900$  Pa. Average, minimum, and maximum values of the parameter  $\tau_G$  are also displayed. In these myoblastic cells, the stiffening phenomenon takes place on a timescale of 600 s on average, with some variability from cell to cell. The value  $\tau_G$  seems to be greater for C2C12 cells than for A549 cells, but the statistics on A549 cells is too poor to conclude about this point.

### Actin recruitment around the bead

Actin is known to be one of the key elements in the regulation of cell rigidity (18,37,38). To investigate its role in the phe-

**TABLE 1** Mechanical parameters calculated from creep measurements performed on A549 cells and C2C12 cells with RGD-coated beads

Cell type	Nb of cells	$\langle \alpha \rangle$	$\sigma_\alpha$	$\langle \log G_0 \rangle$	$\sigma \log G_0$	$G_{0, \text{med}}$ (Pa)	$\langle G_0 \rangle$ (Pa)
A549	22	0.300	0.100	2.48	0.375	305 (−175/+420)	480
C2C12	39	0.316	0.089	2.45	0.475	285 (−140/+570)	375

The “ $\langle \rangle$ ” denote average values,  $\sigma$  the width of the distribution, and  $G_{0, \text{med}}$  is the median value of the viscoelastic modulus  $G_0$ , given by  $G_{0, \text{med}} = 10^{(\log G_0)}$ .

**TABLE 2 Mechanical and actin data for C2C12 cells**

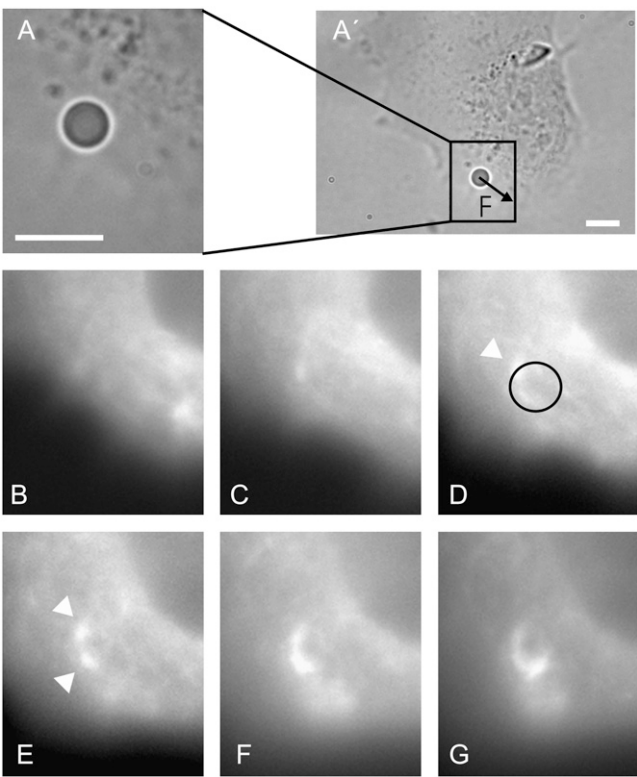
	$G_{0, \text{ini}}$ (Pa)	$G_{0, \text{max}}$ (Pa)	$\tau_G$ (s)	$\tau_Q$ (s)	$\tau'_Q$ (s)
mean	250	900	630	385	555
min	100	420	90	115	225
max	1000	2100	2000	835	875

Data from 11 experiments in which stiffening and actin recruitment were observed; mean, minimum, and maximum values of  $G_{0,\text{ini}}$  and  $G_{0,\text{max}}$ , and of the fitting parameters  $\tau_G$ ,  $\tau_Q$ , and  $\tau'_Q$ .

nomenon of stiffening under stress that we observed, we transfected C2C12 cells with a plasmid coding for GFP-actin and followed the actin quantity around the bead.

In more than half of the experiments, such as the one shown in Fig. 3, bright actin patches appeared at the bead-cell contact. Such patches appeared around beads submitted to a force, while they were never present on other cell-bound beads on which we did not apply any force.

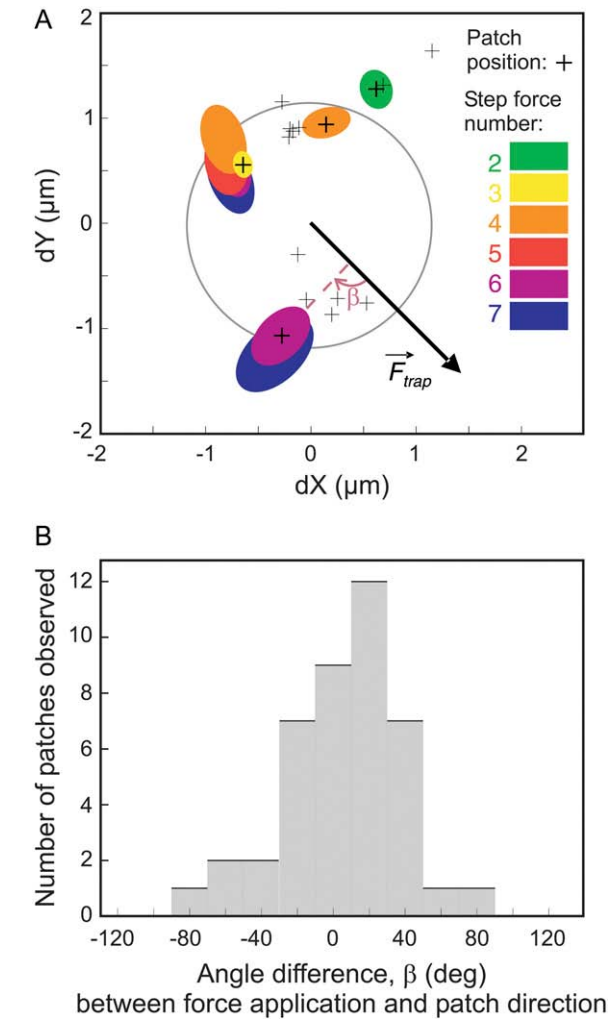
When such actin patches could be detected in an experiment, they appeared after the second or third force step. They started as two or three small elongated dots,  $\sim 0.2 \times 0.5 \mu\text{m}^2$  in size, then grew, and eventually merged into an actin ring



**FIGURE 3** A C2C12 cell during force application: transmission image with an indication of the force direction ( $A'$ ); a zoom around the bead ( $A$ ); fluorescence images of GFP-actin at times  $t_1 = 420$  s ( $B$ ),  $t_3 = 1080$  s ( $C$ ),  $t_5 = 1440$  s ( $D$ ),  $t_7 = 1920$  s ( $E$ ),  $t_9 = 2400$  s ( $F$ ), and  $t_{10} = 2640$  s ( $G$ ). Arrowheads in images  $D$  and  $E$  point at adhesion patches. A circle representing the bead in size and position is superimposed on image  $D$ . (Bars:  $5 \mu\text{m}$ .)

that surrounded the bead (see Fig. 3,  $B-G$ ). These observations are consistent with previous observations of actin recruitment within focal adhesions under force application (4,18). These actin-containing patches, which we observed to develop at the bead-cell contact when a force is applied, are thus probably FA.

In the image analysis procedure (see Materials and Methods), the shape of each actin patch was fitted by an ellipse, defined by its major and minor axes and its orientation angle. This allowed us to follow their direction and size during force application (see Fig. 4  $A$ ). The ellipses were elongated in a direction close to the direction of force application (see Fig. 4  $B$ ): 70% of their orientations differ by less than  $20^\circ$  from the force direction.



**FIGURE 4** ( $A$ ) Graphic of the actin recruited in FA around the bead during one experiment. The arrow gives the force direction. The ellipses are the best fits for the actin patches detected (*crosses* indicate their centers), and are labeled according to the image number on which they are measured. For patches present on step forces number-8 and more, only the centers are displayed. ( $B$ ) Distribution of the actin patches orientations. Angles are calculated relatively to the direction of force application, as displayed on the top panel.

Additional important information was the position of these patches around the bead, with regard to the force direction. They appeared preferentially ahead of and behind the bead, which are the regions of highest strain and stress fields (39), both in compression and elongation. This growth of FA in the direction of the applied force is consistent with previous experimental observations (18) and theoretical predictions (40).

A quantification of the actin contained in these contacts is given by the value  $Q(t)$ . We also measured the global actin density in the network around the bead: it is given by  $Q'(t)$ , the average fluorescence intensity in a disk approximately twice the area of the bead. Both calculations are described in Materials and Methods. Most experiments exhibited an increase in  $Q'$  with time, even when actin dots could not be detected. To test whether this could be attributed to a reinforcement in the actin network around the bead, we measured the average fluorescence intensity  $\delta Q'_i$  in rings of increasing radii  $\delta R_i$  around the bead: from  $\delta R_1 = 2.5$  to  $\delta R_8 = 6.0 \mu\text{m}$  (see Materials and Methods and Fig. 5). This is an estimate of the intermediate-range actin recruitment within the cell. We observed that the actin quantity in those rings increased during the course of the experiments, and that the increase was substantial even far from the bead. Fig. 5 shows the variation of this actin density with the distance  $r$  from the bead center, for different force-application times. The observed decrease of  $\delta Q'$  with  $r$  is fitted by an exponential decay, which yields a cutoff radius of  $\sim 3\text{--}4 \mu\text{m}$ . The actin network is thus reinforced not only at the bead-cell contact, but also up to a distance of several microns from the force-application zone. This length scale is of the same order of magnitude as the characteristic length for stress and strain field decay (39,41).

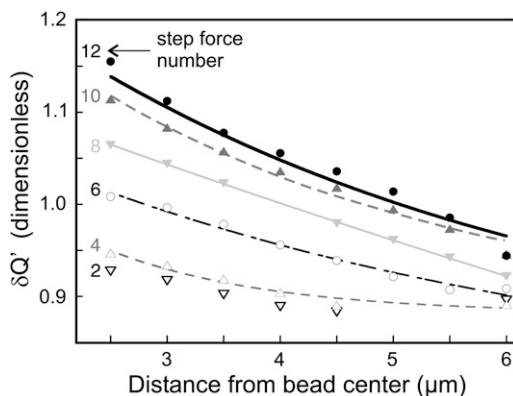


FIGURE 5 Plot of the actin density  $\delta Q'_i$  in successive rings around the bead (of radii  $\delta R_1 = 2.5$  to  $\delta R_8 = 6.0 \mu\text{m}$ ), at different step force application times  $t_k$ ,  $k = 2$  (open down-triangles), 4 (open up-triangles), 6 (open circles), 8 (shaded down-triangles), 10 (shaded up-triangles), and 12 (solid circles). During force application, the actin quantity increases even far from the bead. An exponential decay fit  $\delta Q'_i(r) = A + B \exp(-r/R_c)$  yields a cutoff radius  $R_c$  of  $\sim 3.5 \mu\text{m}$  (1.4, 5.2, 3.25, and  $4.55 \mu\text{m}$ , respectively, for  $t_4$ ,  $t_6$ ,  $t_{10}$ , and  $t_{12}$ ).

On the positive experiments during which we could observe actin recruitment, we eventually stopped the force application to let the cell relax. During this relaxation time, we kept acquiring images, to see whether the fluorescence would decrease. Such a decrease, down to the intensity level observed before force application, was observed in more than half of the cases, but not all of them. Due to this variability in the cells relaxation behavior, we cannot conclude on any relaxation timescale.

Control experiments were performed to ensure that the actin recruitment was not due to attraction of cell material toward the optical trap. We performed the same temporal series of tweezers application as in the real experiments, but without trapping any bead on the cell. We did not see any increase in the actin quantity around the laser application zone.

### Correlation between the rigidity increase and actin recruitment

To compare the kinetics of actin recruitment observed in all the experiments, we plotted the time evolution of both dimensionless actin quantities,  $q(t) = (Q(t) - Q_{\min})/(Q_{\max} - Q_{\min})$  and  $q'(t) = (Q'(t) - Q'_{\min})/(Q'_{\max} - Q'_{\min})$ , that are defined in the same way as  $g(t)$ .

We fitted these data by sigmoids with a similar set of three parameters as for  $g$ : ( $q_0$ ,  $q_f$ ,  $\tau_Q$ ) and ( $q'_0$ ,  $q'_f$ ,  $\tau'_Q$ ). Fig. 6 shows the result of an experiment in which  $g$ ,  $q$ , and  $q'$  increase with very similar behaviors. The most interesting parameters of the fit, the timescales, are  $\tau_G = 612 \text{ s}$ ,  $\tau_Q = 300 \text{ s}$ , and  $\tau'_Q = 470 \text{ s}$ , in this example. As summarized in Table 2, for all the cells tested, we observed typical recruitment times of a few hundreds of seconds. It should be noted that, despite cell-to-

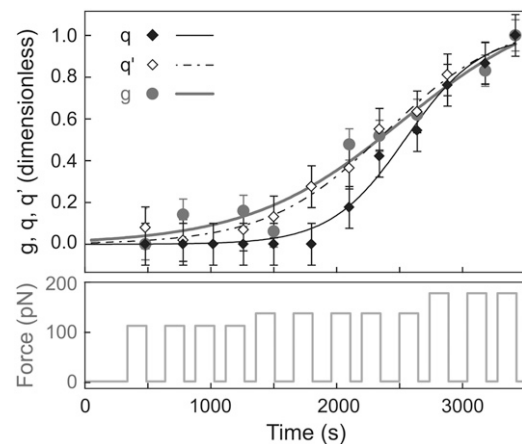


FIGURE 6 Normalized cell viscoelastic modulus  $g(t)$  (shaded dots), actin quantities  $q(t)$  (solid diamonds), and  $q'(t)$  (open diamonds) versus time, during a series of step-force applications. Fitting this experiment by a sigmoid yields the parameters  $\{q_0 = 1.9 \cdot 10^{-4}, q_f = 1.01, \tau_Q = 300 \text{ s}\}$ ;  $\{q'_0 = 6.2 \cdot 10^{-3}, q'_f = 1.03, \tau'_Q = 471 \text{ s}\}$ ; and  $\{g_0 = 1.6 \cdot 10^{-3}, g_f = 1.2, \tau_G = 612 \text{ s}\}$ .

cell variability, scattering of the timescales  $\tau_G$ ,  $\tau_Q$ , and  $\tau'_Q$  turns out to be rather small.

We must also take into account the waiting time that is left between two successive force steps, which is approximately equal to the force application duration itself. We can estimate that the force is applied during an effective time  $t_{\text{eff}}$ , which is half the total time  $t$ . Effective timescales for stiffening and actin recruitment can also be roughly estimated as half the mean measured times:  $\tau_{G\text{eff}} \simeq \tau_G/2 \simeq 315$  s,  $\tau_{Q\text{eff}} \simeq 192$  s, and  $\tau'_{Q\text{eff}} \simeq 277$  s.

The increase in  $G_0$  appears highly correlated to the actin recruitment around the bead. The bead-cell contact strengthening exhibits a sigmoidlike dynamics, with an effective rising time  $\tau_{Q\text{eff}}$  of  $\sim 200$  s. However, in most of the experiments, the effective rigidification time  $\tau_{G\text{eff}}$  is closer to the rising time for the overall actin network density  $\tau'_{Q\text{eff}}$  than to  $\tau_{Q\text{eff}}$ . This is also evident in the average values: both  $\tau_{G\text{eff}}$  and  $\tau'_{Q\text{eff}}$  are very close to 300 s. This shows that the reinforcement of the actin network results in a greater cell rigidity. The increase in the measured rigidity is thus very dependent on the actin network densification, and not only on the strengthening of the contacts as previously reported (12).

## CONCLUSION

This work is the first attempt to quantify the dynamics of both cell stiffening and actin recruitment in response to a controlled external stress. We evidence a mechanical strengthening of cells in response to force application, and a reinforcement both of the cell-substrate contact and of the local actin network in the vicinity of the force application zone, and up to several micrometers from it. The rising times for cell rigidity and actin quantity are  $\sim 300$  s for C2C12 cells.

In this study, we use mere wide-field epifluorescence images. This allows us to perform a semiquantitative analysis of the local actin density. We do not provide results regarding the dynamics of single actin filaments or the mechanisms underlying actin network reorganization. The increase in the actin quantity may be due to a densification or a broadening of the actin cortex in this zone, and/or to a more global reorganization of the filaments within the cell, allowing for instance new actin bundles to grow from or toward the force application zone. Addressing these issues will require the use of more sophisticated fluorescence observation techniques like confocal microscopy, fluorescence recovery after photobleaching (42), or fluorescence speckle microscopy (43). This could help elucidate the precise cytoskeleton dynamics underlying the recruitment that we evidence here.

## SUPPLEMENTARY MATERIAL

To view all of the supplemental files associated with this article, visit [www.biophysj.org](http://www.biophysj.org).

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